



## ATTACHMENT B Amendments to the Claims

This listing of claims will replace all prior versions, and listing, of claims in the application.

1. (currently amended) A method of managing the kinematics of a seat, said seat having at least three seat elements that are able to move with respect to each other and said seat having at least two actuators actuatable in different directions for moving the three elements with respect to each other, wherein, when actuating a first actuator of said at least two actuators <sup>of the first actuator</sup> ~~is actuated~~ in one direction, it said actuating step always includes a step of actuating a second actuator of said at least two actuators first of all in a given direction and then in ~~the~~ an opposite direction to said given direction.

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2. (currently amended) A method according to Claim 1, wherein the actuating step of the second actuator in said given direction is effected for a first predetermined duration.

3. (currently amended) A method according to Claim 2, wherein the actuating step of the second actuator in said opposite direction is effected for a second predetermined duration.

4. (currently amended) A method according to Claim 3, wherein the first and second predetermined durations are such that, according to ~~the~~ a speed of movement of the second actuator in the given direction and in the opposite direction, the movement travels in both the given and opposite directions are substantially identical.

5. (currently amended) A method according to Claim 1, wherein, before the movement step of actuating the second actuator in said given direction, ~~it the step of activating the second actuator~~ includes a step of measuring and storing the a current position of the second actuator, and wherein the actuating step of the second actuator in said opposite direction is effected at most until the second actuator returns to said stored position.

6. (currently amended) A method according to claim 1,

wherein the method includes a step of monitoring at least one variable characteristic of ~~the~~a force produced by the second actuator, during ~~its use~~actuation thereof in the said opposite direction, and a step of estimating at least one predetermined evaluation criterion relating to a characteristic variable or variables, and

wherein the method includes a step of actuating the second actuator in accordance with a predefined control instruction, ending ~~its~~the movement of the second actuator in the opposite direction, when at least one of the predetermined evaluation criteria is satisfied.

7. (currently amended) A method according to Claim 6, wherein said predetermined control instruction is an instruction chosen from ~~the~~a group consisting of ~~the~~a stoppage of the second actuator and ~~the~~a driving of the second actuator in said given direction.

8. (currently amended) A method according to Claim 6, wherein the second actuator consumes electric current and wherein at least one variable characteristic of the force produced is a variable characteristic of ~~the~~an electric current consumed by the second actuator chosen from ~~the~~a group consisting of ~~the~~an intensity consumed by the second actuator and a drift with respect to ~~the~~a time of the intensity consumed by the second actuator.

9. (currently amended) A seat having at least three seat elements able to move with respect to each other and at least two actuators for moving the three elements with respect to each other, wherein the seat further has

means of actuating a first actuator of said at least two actuators in one direction and

automatic means of actuating a second actuator of said at least two actuators [first of all] in a given direction and then in an opposite direction, whenever said first actuator is actuated in said one direction.

10. (currently amended) A seat according to Claim 9, further including:

a movable squab;

a back rest articulated on the squab;

a leg rest articulated on the squab;

a foot rest mounted so as to be able to move with respect to the leg rest; and

wherein said first actuator is adapted for the a conjoint movement of the back rest and of the squab by providing the a lowering of the squab when the back rest is raised up; and

wherein the second actuator is adapted for the a movement of the foot rest with respect to the leg rest.

11. (currently amended) A seat according to Claim 9, further including:

a movable squab;

a back rest articulated on the squab;

a leg rest articulated on the squab; and

wherein said first actuator is adapted for the a conjoint movement of the back rest and of the squab by providing the a lowering of the squab when the back rest is raised up; and

wherein said second actuator is adapted for the a movement of the leg rest with respect to the squab.